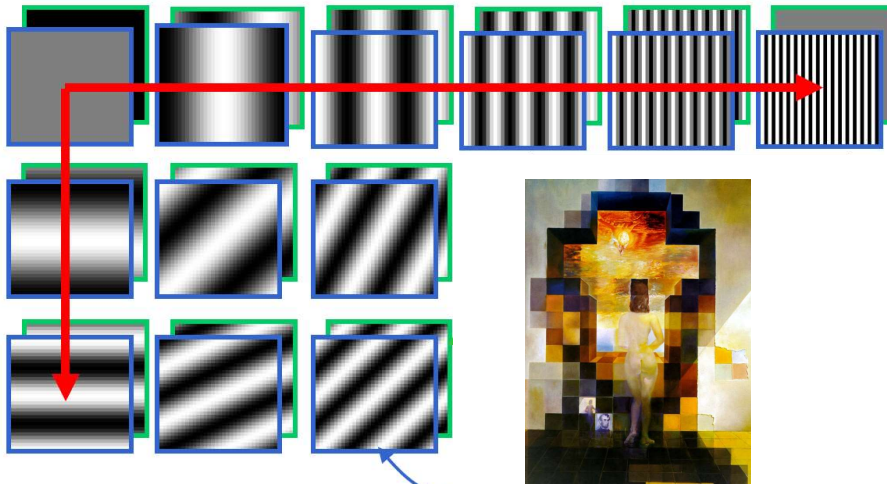


## 2d Fourier Transform

$$F(u, v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi \left[ \frac{ux}{M} + \frac{vy}{N} \right]}$$

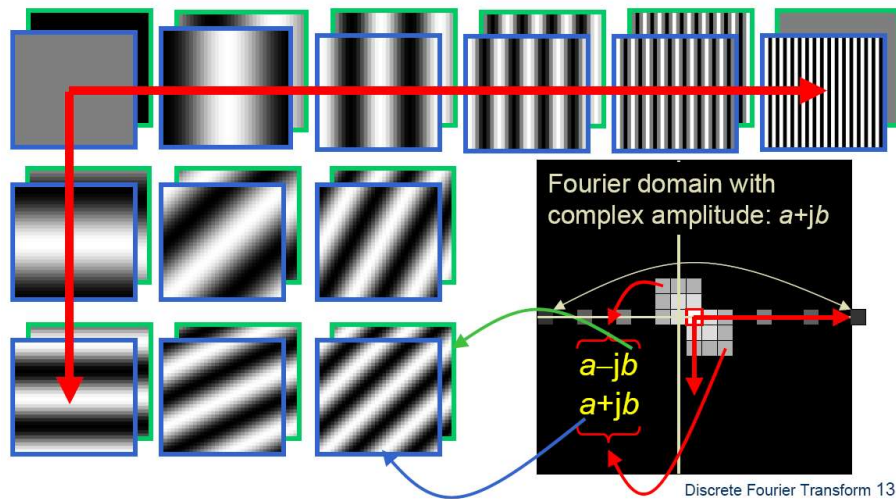
## Fourier Bases

Teases away fast vs. slow changes in the image.



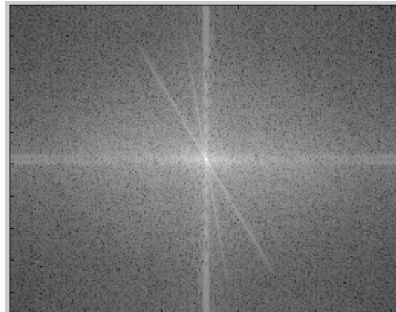
This change of basis is the Fourier Transform

## Fourier Bases

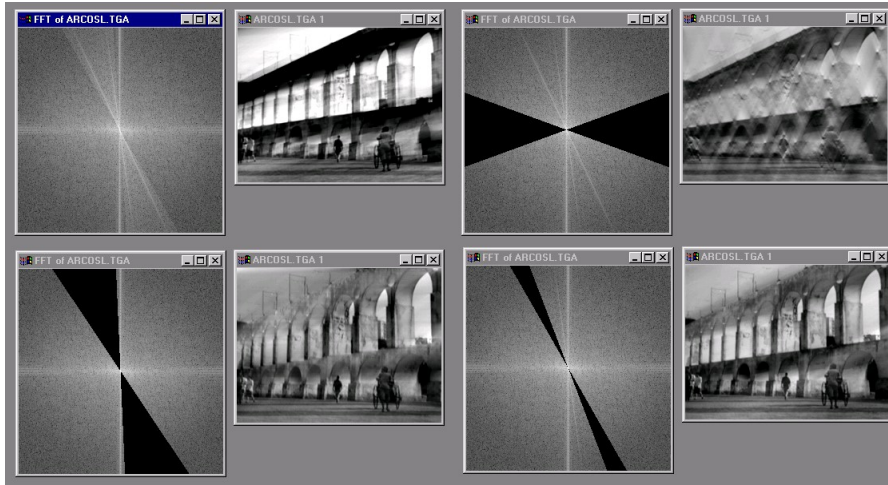


in Matlab, check out: `imagesc(log(abs(fftshift(fft2(im)))));`

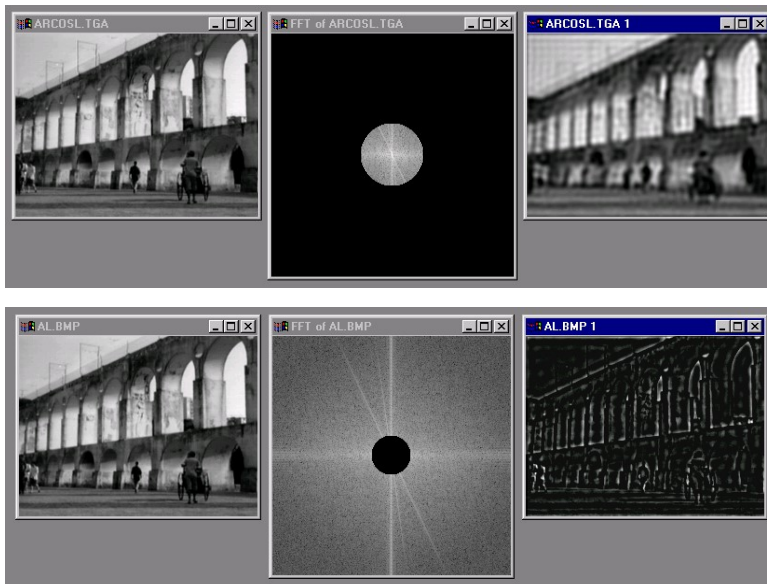
## Man-made Scene



Can change spectrum, then reconstruct

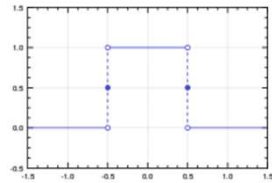


Low and High Pass filtering

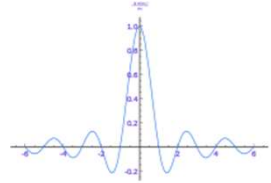


## Sinc Filter

- What is the spatial representation of the hard cutoff in the frequency domain?



Frequency Domain



Spatial Domain

## The Convolution Theorem

- The Fourier transform of the convolution of two functions is the product of their Fourier transforms

$$F[g * h] = F[g]F[h]$$

- **Convolution** in spatial domain is equivalent to **multiplication** in frequency domain!

$$g * h = F^{-1}[F[g]F[h]]$$

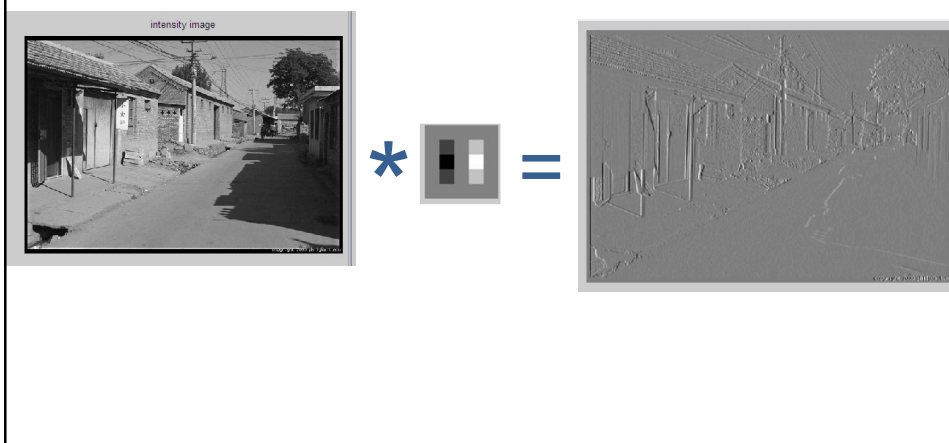
## Properties of Fourier Transforms

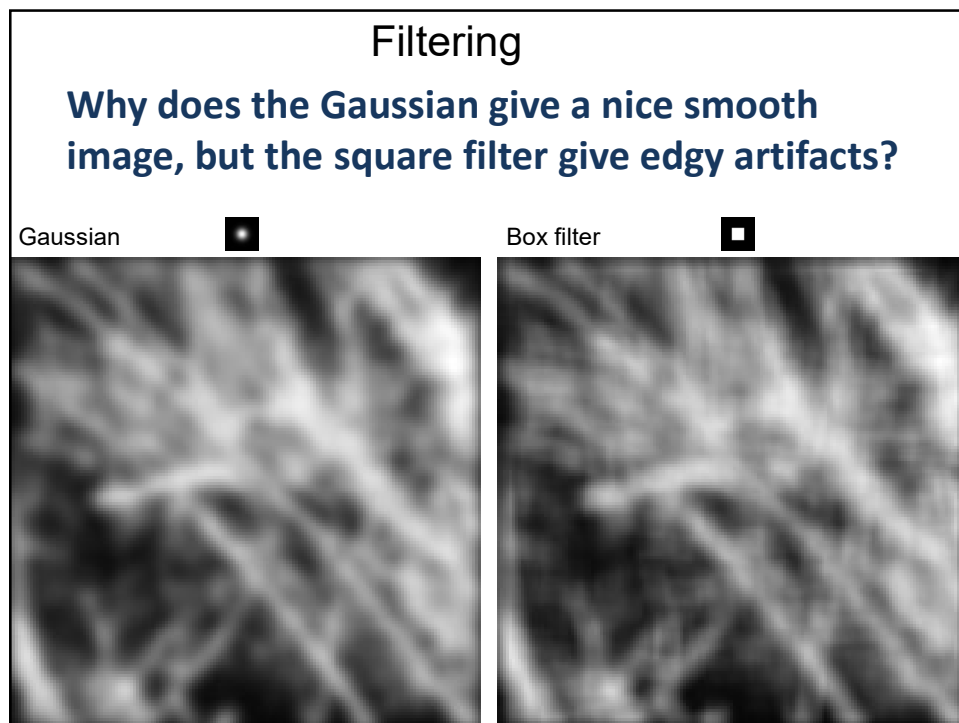
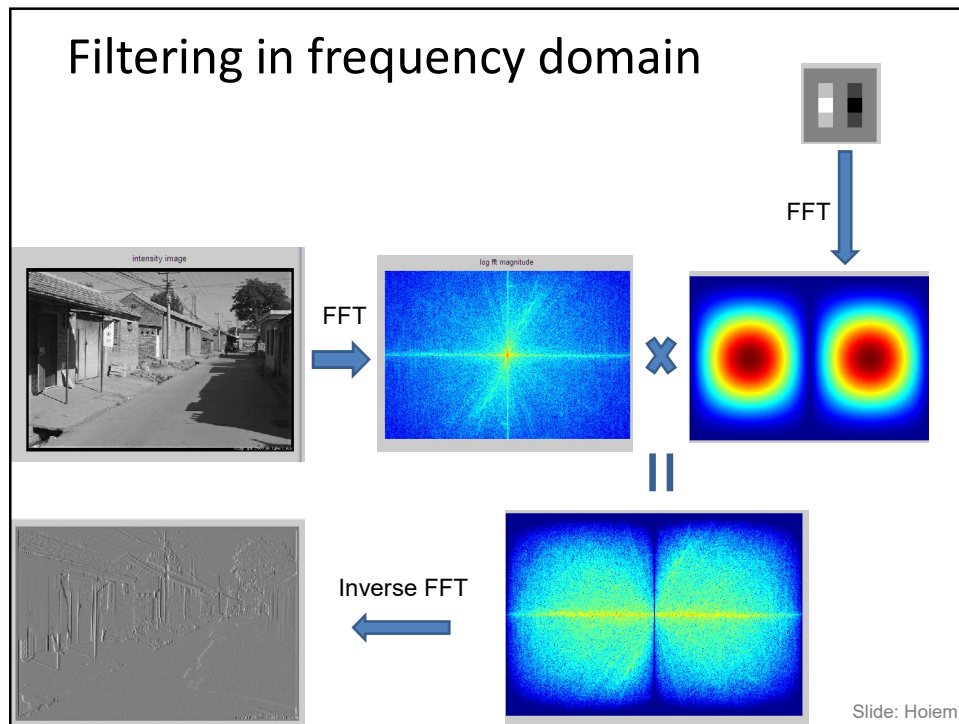
- Linearity  $\mathcal{F}[ax(t) + by(t)] = a\mathcal{F}[x(t)] + b\mathcal{F}[y(t)]$
- Fourier transform of a real signal is symmetric about the origin
- The energy of the signal is the same as the energy of its Fourier transform

See Szeliski Book (3.4)

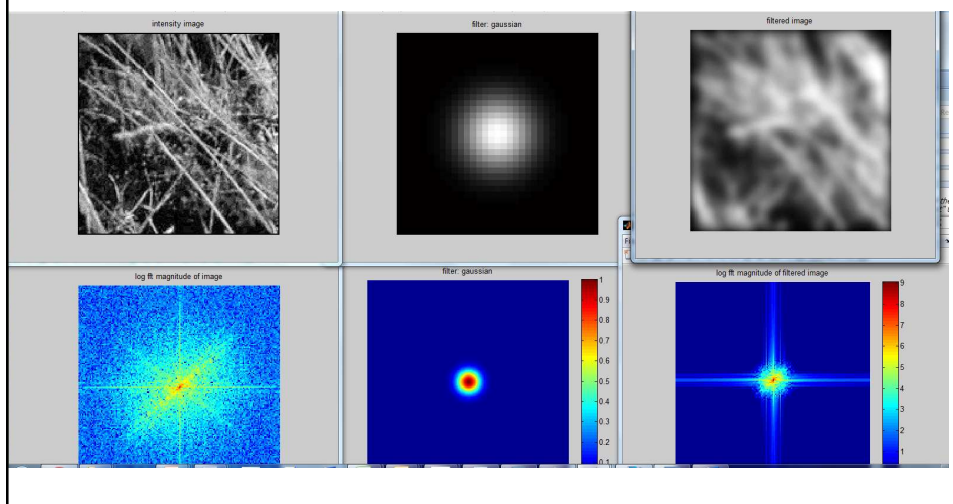
## Filtering in spatial domain

1	0	-1
2	0	-2
1	0	-1

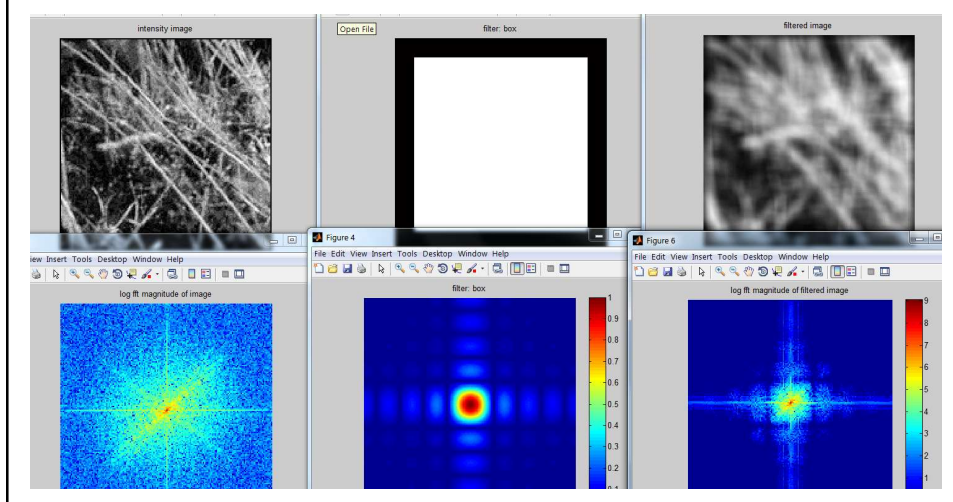




## Gaussian



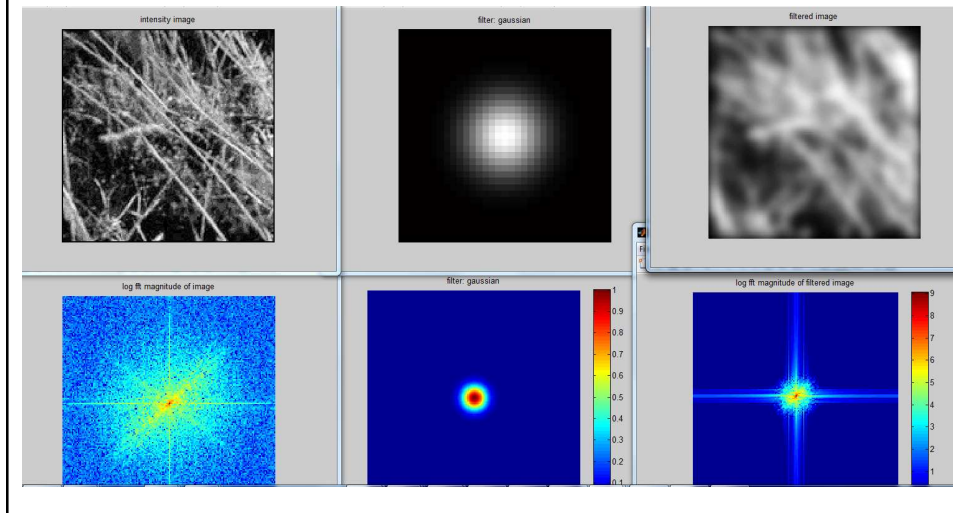
## Box Filter



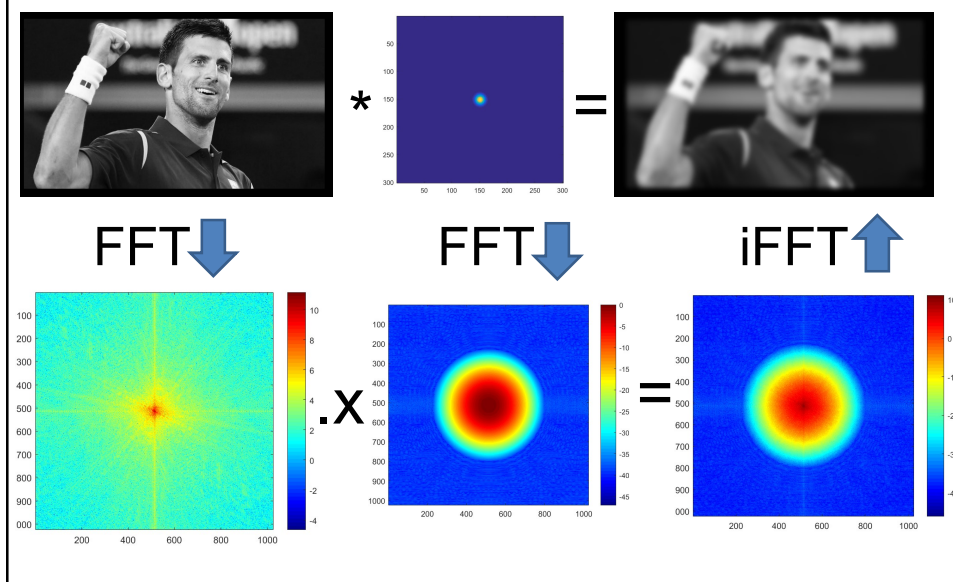


## But you can't invert multiplication by 0

- But it's not quite zero, is it...

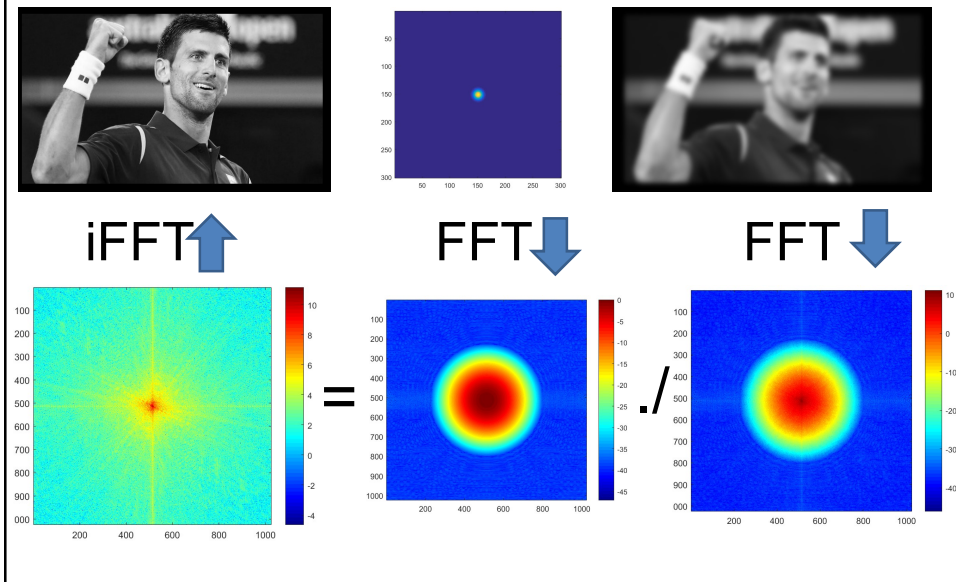


## Convolution

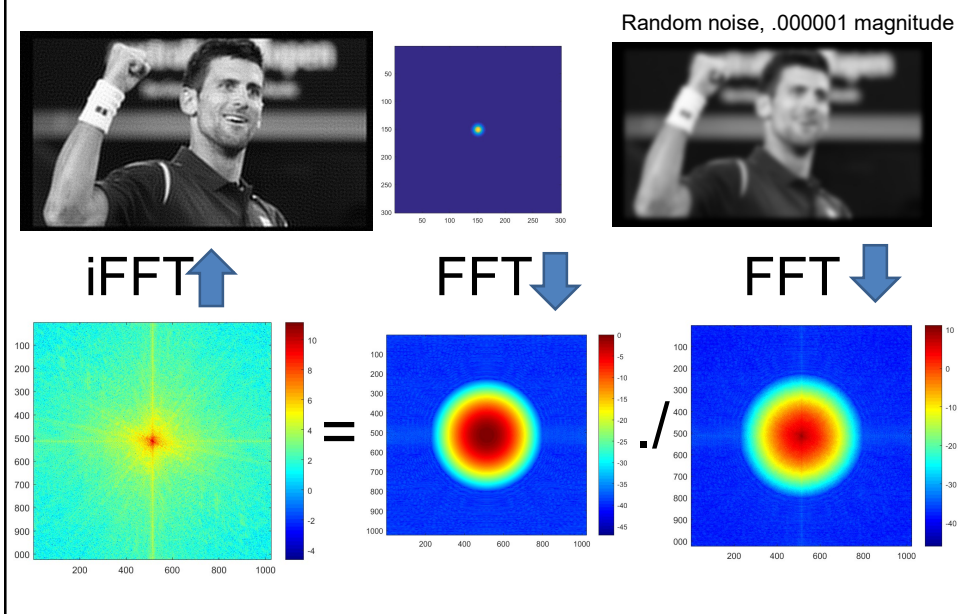




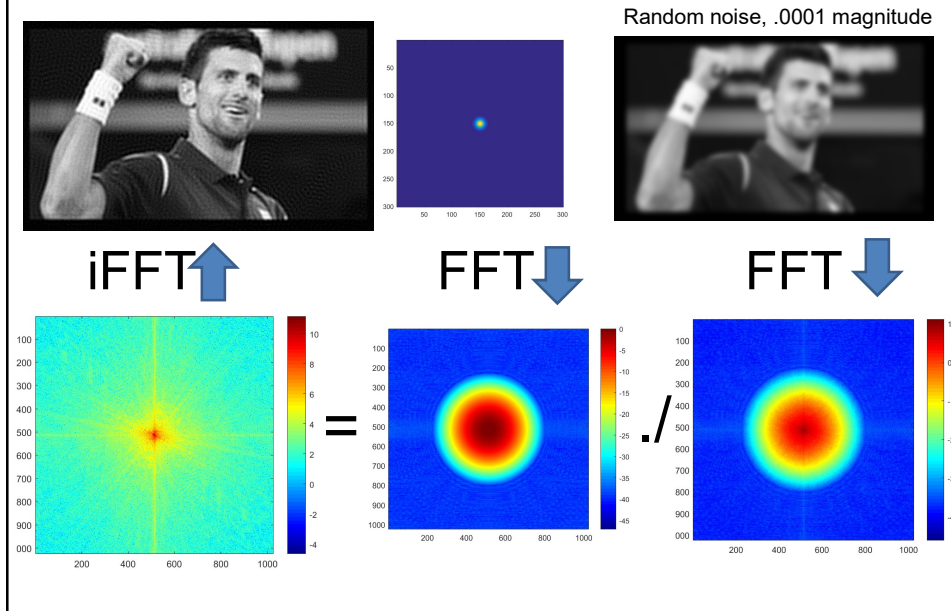
# Deconvolution?



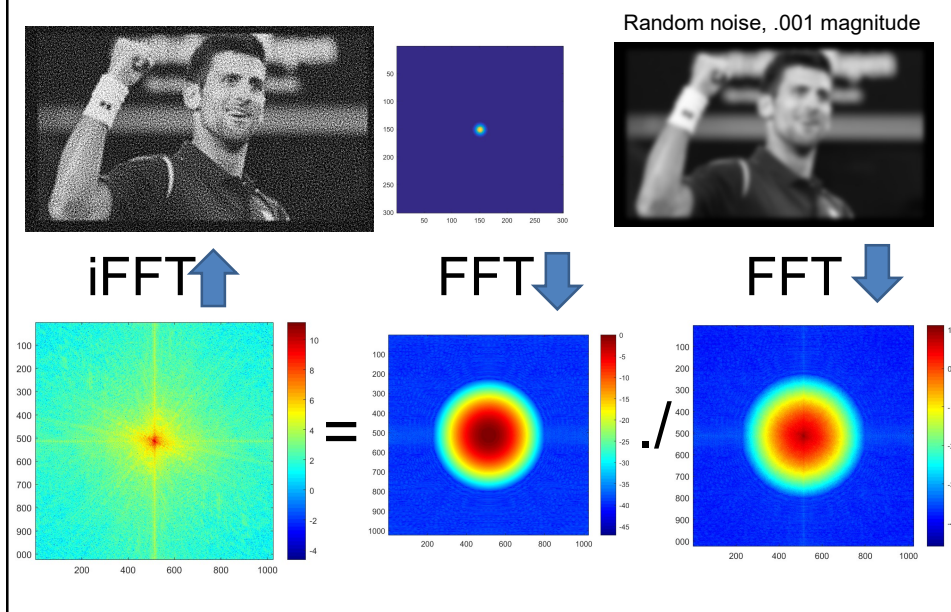
# But under more realistic conditions



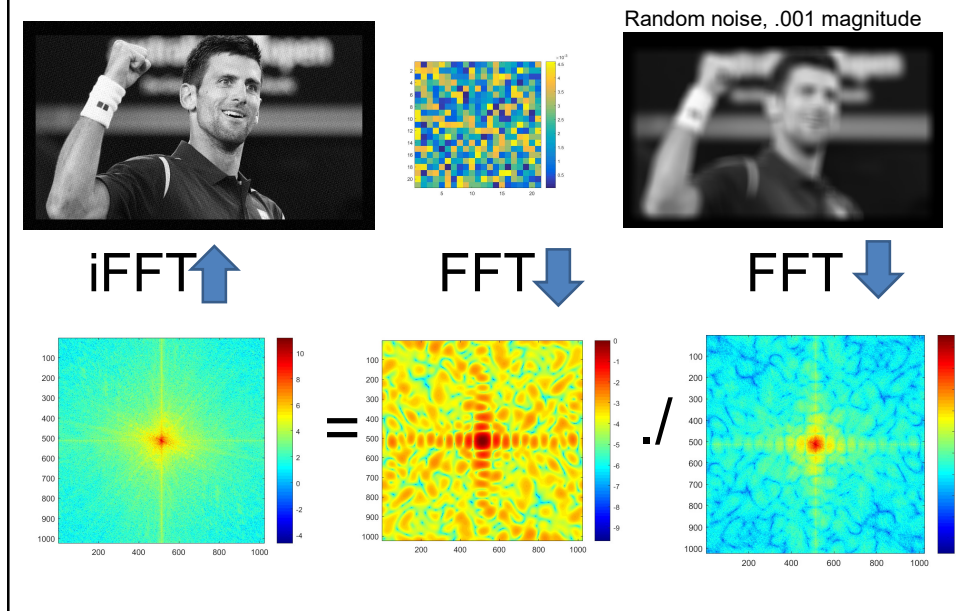
## But under more realistic conditions



## But under more realistic conditions



With a random filter...



Deconvolution is hard

- Active research area.
- Even if you know the filter (non-blind deconvolution), it is still very hard and requires strong *regularization*.
- If you don't know the filter (blind deconvolution) it is harder still.

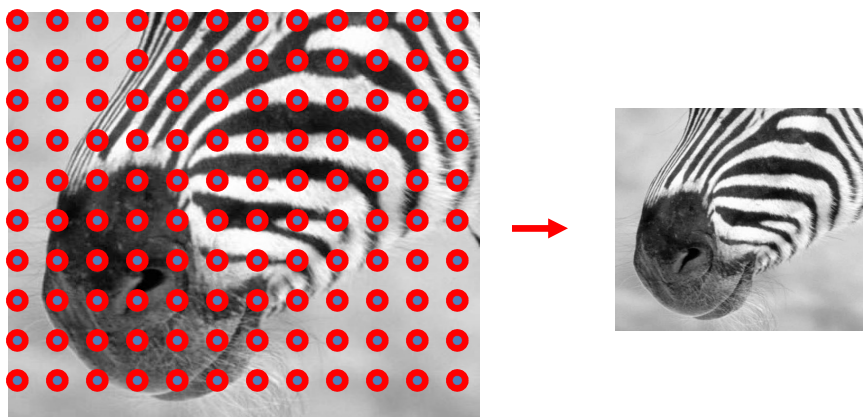
## Sampling

Why does a lower resolution image still make sense to us? What do we lose?



Image: <http://www.flickr.com/photos/igorms/136916757/>

## Subsampling by a factor of 2



Throw away every other row and column to create a 1/2 size image

## Aliasing problem

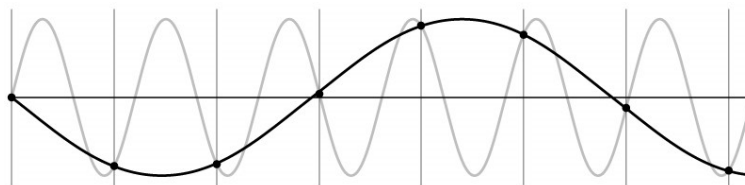
- 1D example (sinewave):



Source: S. Marschner

## Aliasing problem

- 1D example (sinewave):



Source: S. Marschner

## Aliasing problem

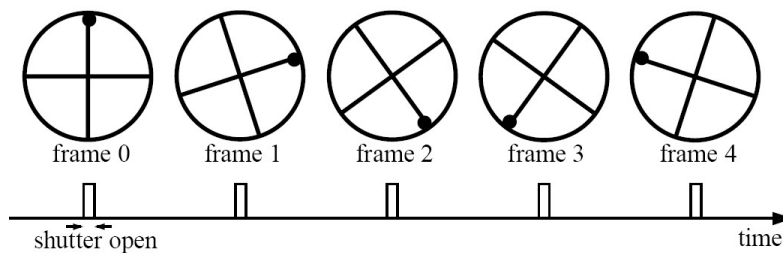
- Sub-sampling may be dangerous....
- Characteristic errors may appear:
  - “car wheels rolling the wrong way in movies”
  - “Checkerboards disintegrate in ray tracing”
  - “Striped shirts look funny on color television”

Source: D. Forsyth

## Aliasing in video

Imagine a spoked wheel moving to the right (rotating clockwise).  
Mark wheel with dot so we can see what's happening.

If camera shutter is only open for a fraction of a frame time (frame time = 1/30 sec. for video, 1/24 sec. for film):



Without dot, wheel appears to be rotating slowly backwards!  
(counterclockwise)

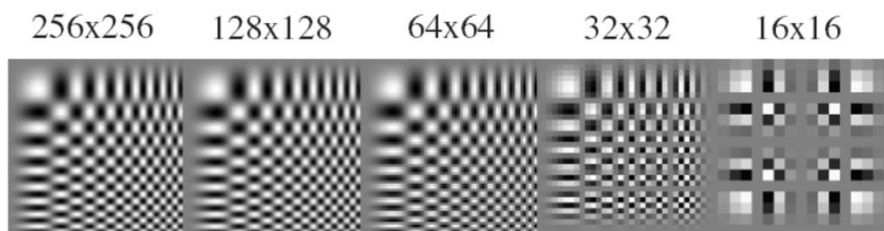
Slide by Steve Seitz

## Aliasing in graphics



Source: A. Efros

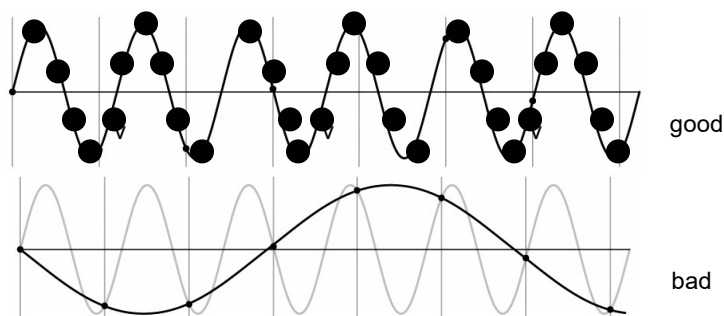
## Sampling and aliasing





## Nyquist-Shannon Sampling Theorem

- When sampling a signal at discrete intervals, the sampling frequency must be  $\geq 2 \times f_{\max}$
- $f_{\max}$  = max frequency of the input signal
- This will allow to reconstruct the original perfectly from the sampled version



## Anti-aliasing

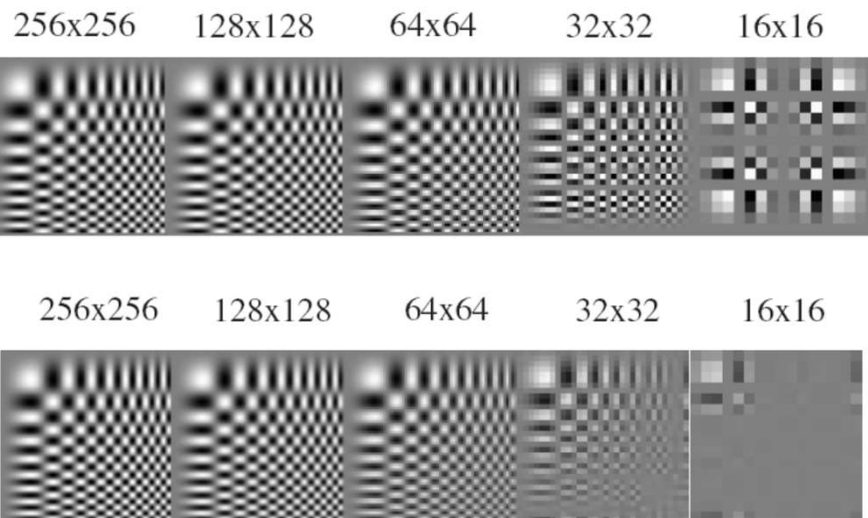
Solutions:

- Sample more often
- Get rid of all frequencies that are greater than half the new sampling frequency
  - Will lose information
  - But it's better than aliasing
  - Apply a smoothing filter

## Algorithm for downsampling by factor of 2

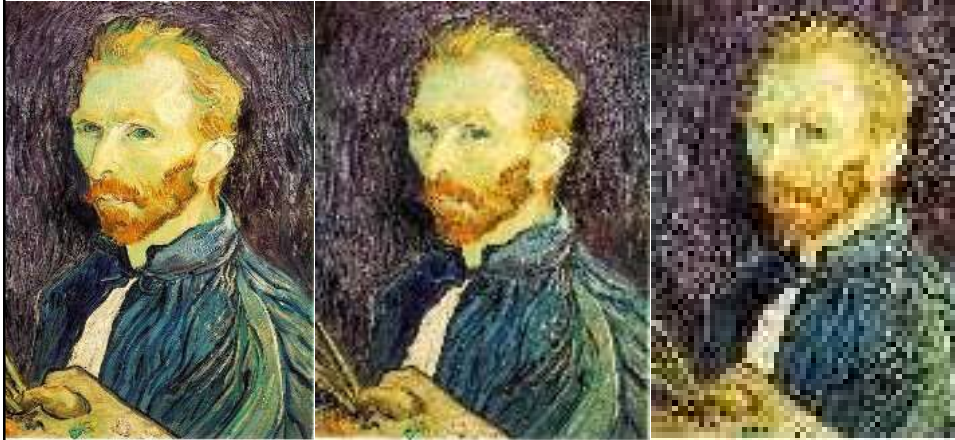
1. Start with image(h, w)
2. Apply low-pass filter  
`im_blur = imfilter(image, fspecial('gaussian', 7, 1))`
3. Sample every other pixel  
`im_small = im_blur(1:2:end, 1:2:end);`

## Anti-aliasing



Forsyth and Ponce 2002

### Subsampling without pre-filtering



1/2

1/4 (2x zoom)

1/8 (4x zoom)

Slide by Steve Seitz

### Subsampling with Gaussian pre-filtering



Gaussian 1/2

G 1/4

G 1/8

Slide by Steve Seitz