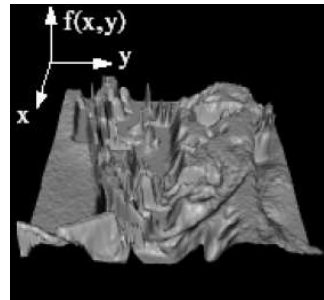


What is an image?

- Ideally, we think of an **image** as a 2-dimensional light intensity function, $f(x,y)$, where x and y are spatial coordinates, and f at (x,y) is related to the brightness or color of the image at that point.
- In practice, most images are defined over a rectangle.
- Continuous in amplitude („continuous-tone“)
- Continuous in space: no pixels!

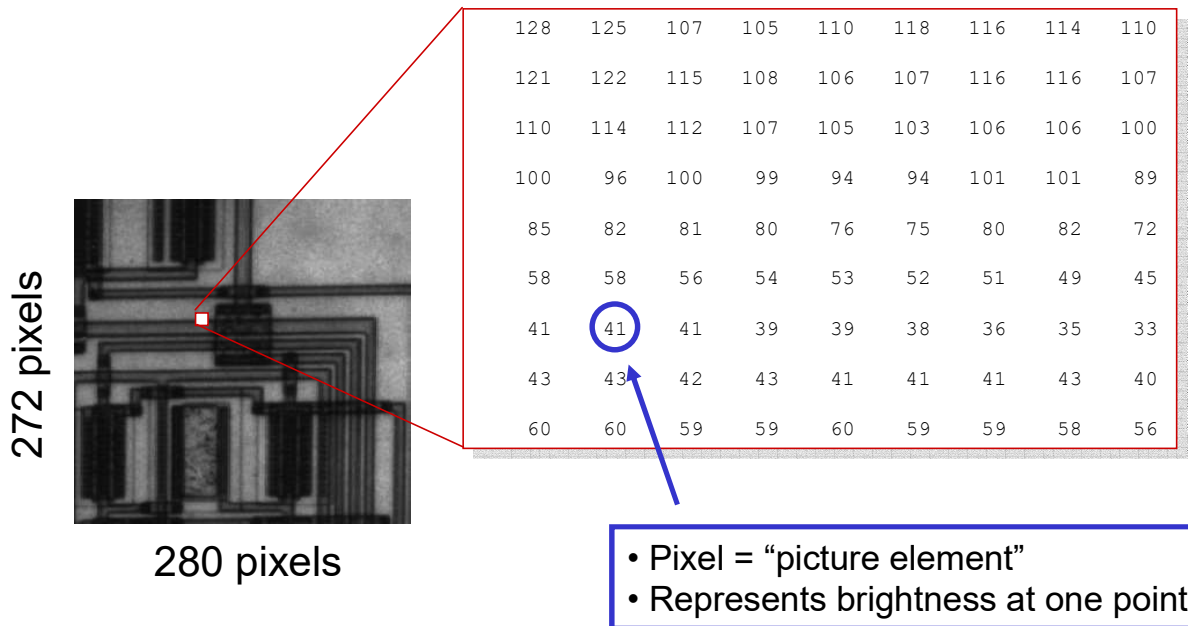


Digital Images and Pixels

- A **digital image** is the representation of a continuous image $f(x,y)$ by a 2-d array of discrete samples. The amplitude of each sample is quantized to be represented by a finite number of bits.
- Each element of the 2-d array of samples is called a **pixel** or **pel** (from „picture element“)
- Pixels are point samples, without extent.
- A pixel is not:
 - Round, square, or rectangular
 - An element of an image sensor
 - An element of a display



A Digital Image is Represented by Numbers



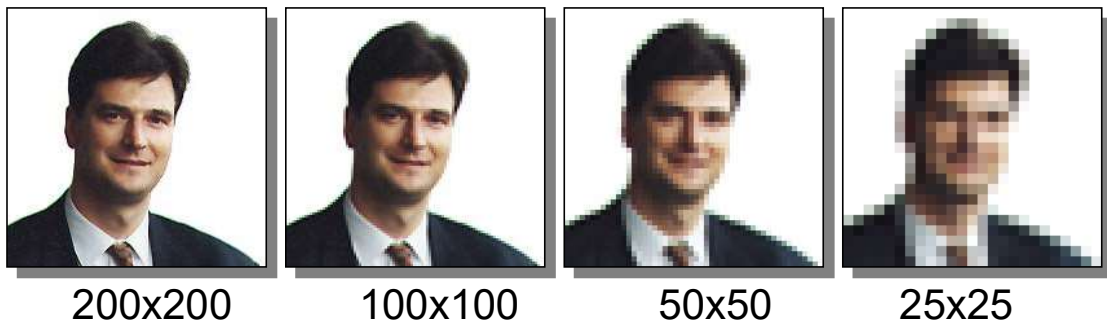
A digital image can be represented as a matrix

$$\mathbf{f} = \begin{matrix} & \xrightarrow{x} & & & & & & & \\ \left[\begin{array}{cccc} f(0,0) & f(1,0) & \cdots & f(N-1,0) \\ f(0,1) & f(1,1) & \cdots & f(N-1,1) \\ \vdots & \vdots & & \vdots \\ f(0,L-1) & f(1,L-1) & \cdots & f(N-1,L-1) \end{array} \right] & \downarrow y & & & & & & &
 \end{matrix}$$

- The pixel values $f(x,y)$ are sorted into the matrix in „natural“ order, with x corresponding to the column and y to the row index. Matlab uses this convention. This results in $f(x,y) = f_{yx}$, where f_{yx} denotes an individual element in common matrix notation.
- For a color image, \mathbf{f} might be one of the components.



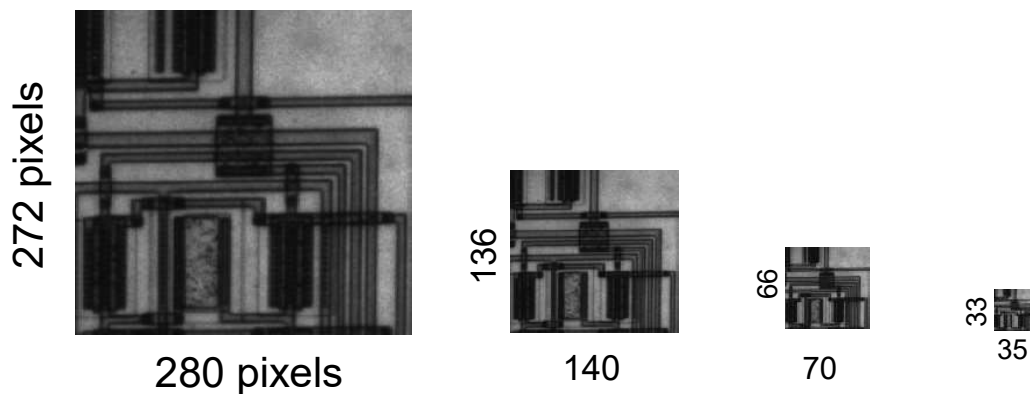
Image Size and Resolution



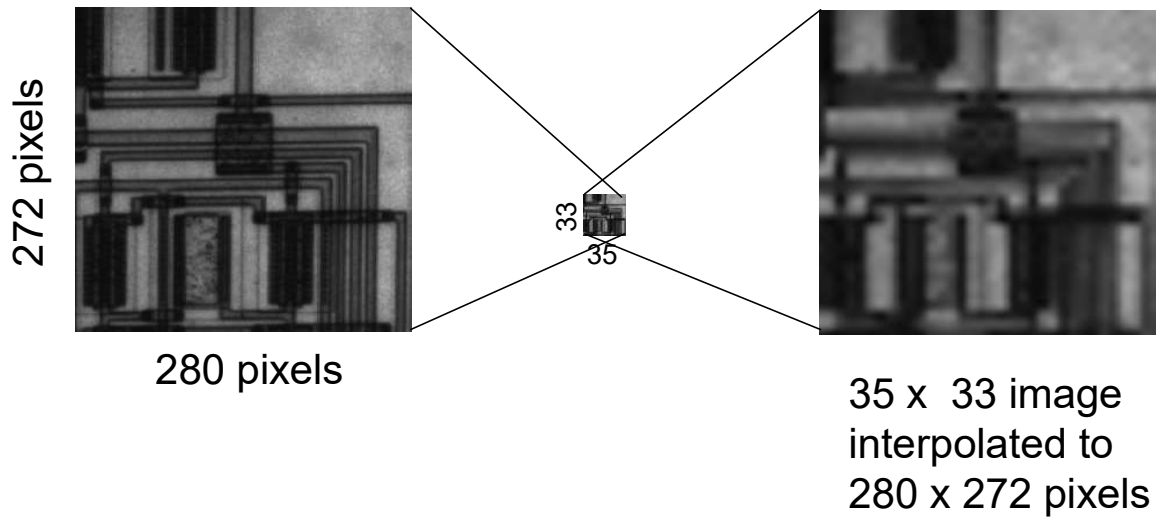
- These images were produced by simply picking every n -th sample horizontally and vertically and replicating that value $n \times n$ times.
- We can do better
 - *prefiltering before subsampling to avoid aliasing*
 - *Smooth interpolation*



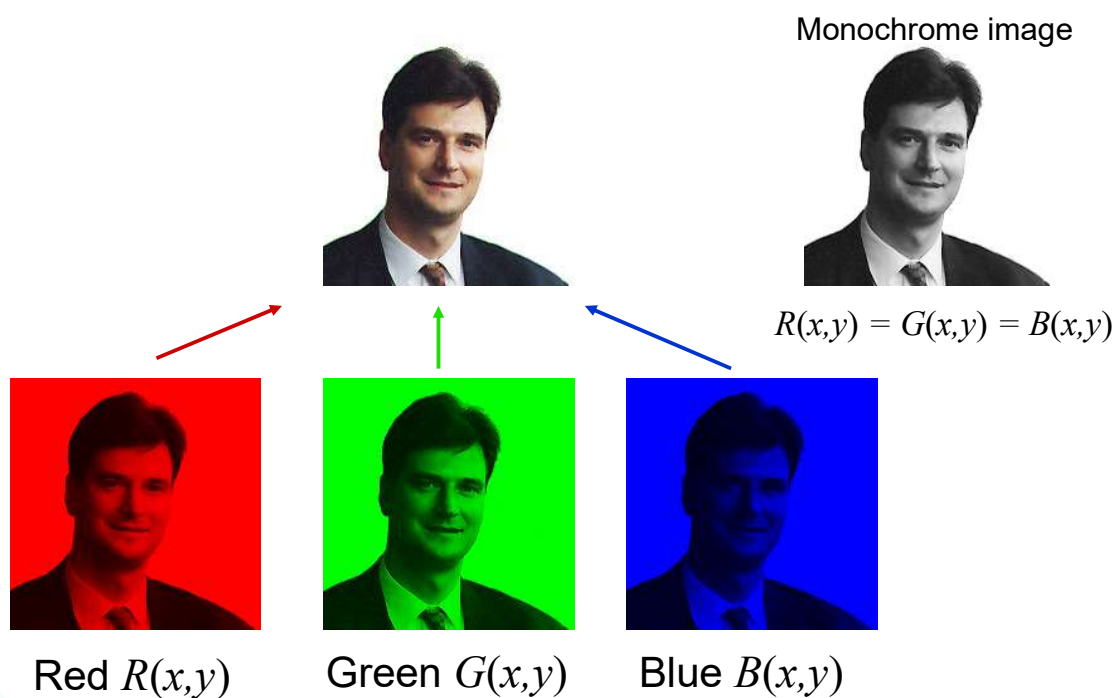
Images of Different Sizes



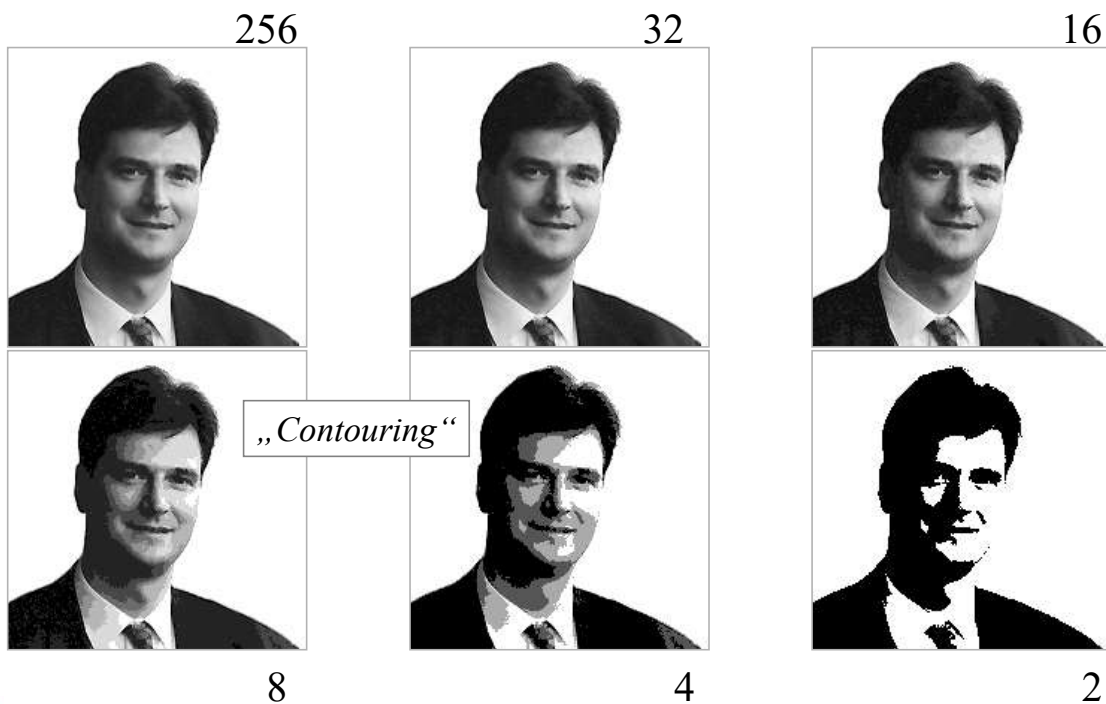
Fewer Pixels Mean Lower Spatial Resolution



Color Components

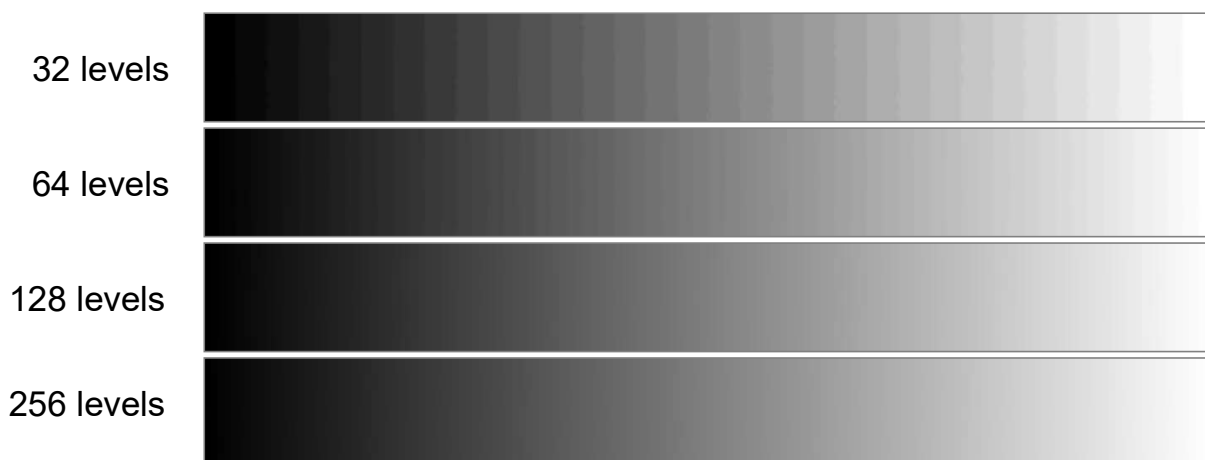


Different numbers of gray levels



How many gray levels are required?

- Contouring is most visible for a ramp



- Digital images typically are quantized to 256 gray levels.



Storage requirements for digital images

- Image $L \times N$ pixels, 2^B gray levels, c color components

$$\text{Size} = L \times N \times B \times c$$

– Example: $L=N=512$, $B=8$, $c=1$ (i.e., monochrome)

Size = 2,097,152 bits (or 256 kByte)

– Example: $L \times N=1024 \times 1280$, $B=8$, $c=3$ (24 bit RGB image)

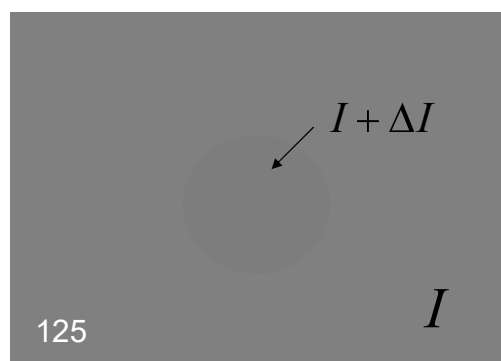
Size = 31,457,280 bits (or 3.75 MByte)

- Much less with (lossy) compression!



Brightness discrimination experiment

- Can you see the circle?



Note: I is luminance, measured in cd/m^2

- Visibility threshold

$$\Delta I / I \approx \text{const.} \approx 1 \dots 2\%$$

„Weber fraction“
„Weber’s Law“



Contrast with 8 Bits According to Weber's Law

- Assume that the luminance difference between two successive representative levels is just at visibility threshold

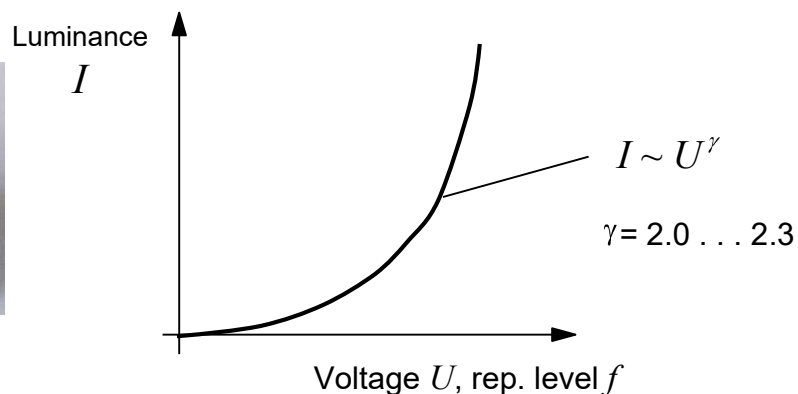
$$\frac{I_{\max}}{I_{\min}} = (1 + \text{const.})^{255}$$

- For $\text{const.} = 0.01 \dots 0.02$ $\frac{I_{\max}}{I_{\min}} = 13 \dots 156$
- Typical display contrast
 - Cathode ray tube 100:1
 - Print on paper 10:1
- Suggests uniform quantization in the $\log(I)$ domain



Gamma characteristic

- Cathode ray tubes (CRT) are nonlinear

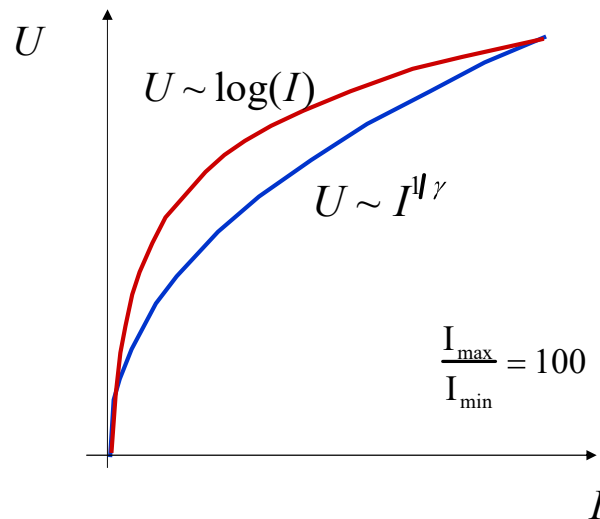


- Cameras contain γ -predistortion circuit

$$U \sim I^{1/\gamma}$$



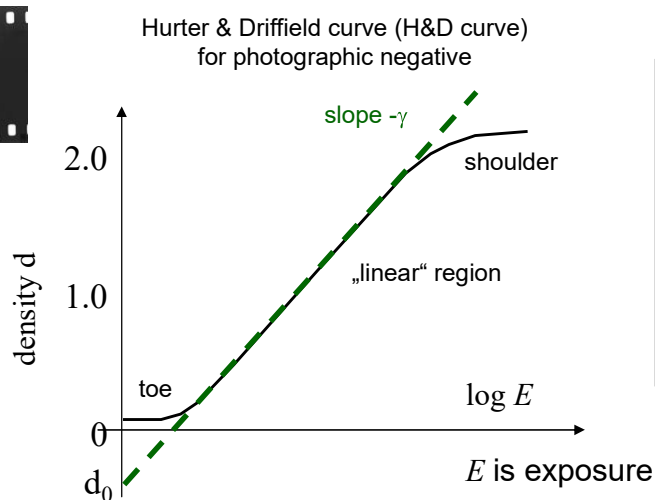
log vs. γ -predistortion



- Similar enough for most practical applications



Photographic film



Luminance

$$\begin{aligned}
 I &= I_0 \cdot 10^{-d} \\
 &= I_0 \cdot 10^{-(\gamma \log E + d_0)} \\
 &= I_0 \cdot 10^{-d_0} \cdot E^{-\gamma}
 \end{aligned}$$

- γ measures film contrast
 - General purpose films: $\gamma = -0.7 \dots -1.0$
 - High-contrast films: $\gamma = -1.5 \dots -10$
- Lower speed films tend to have higher absolute γ

